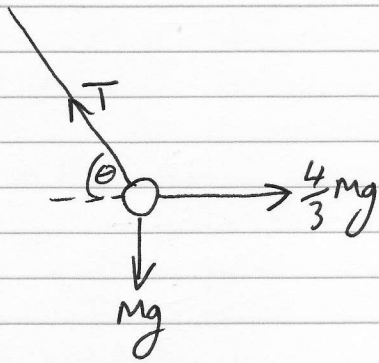


Q2



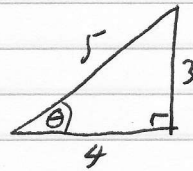
$$(a) \text{ HL } T = \frac{3Mg x}{a} \quad \text{--- (1)}$$

$$\Sigma F_y: T \sin \theta = Mg \quad \text{--- (2)}$$

$$\Sigma F_x: \frac{4Mg}{3} - T \cos \theta = 0$$

$$T \cos \theta = \frac{4Mg}{3} \quad \text{--- (3)}$$

$$(2) \div (3) \quad \tan \theta = \frac{3}{4}$$



$$\therefore \sin \theta = \frac{3}{5}$$

$$\text{in (2)} \quad T \times \frac{3}{5} = Mg$$

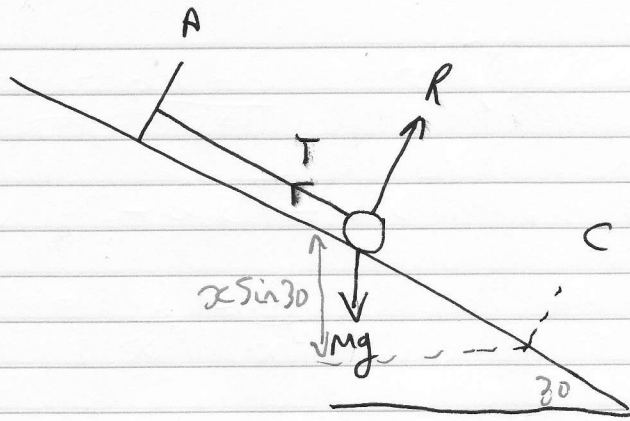
$$T = \frac{5}{3} Mg$$

$$(b) \text{ in (1)} \quad \frac{5Mg}{3} = \frac{3Mg x}{a}$$

$$x = \frac{5a}{9}$$

$$\text{Now energy} = \frac{1}{2} k x^2 = \frac{3Mg}{2a} \left(\frac{5a}{9} \right)^2 = \frac{25}{54} Mga$$

(5)



(a) $BC = \text{extension} = x$

No change in KE

@ C loss in PE = gain in EPE

$$Mg x \sin 30 = \frac{\lambda x^2}{2a}$$

$$\frac{Mg x}{2} = \frac{6Mg x^2}{2a}$$

$$x = \frac{a}{6}$$

$$\therefore AC = \frac{a}{6} + a = \frac{7a}{6}$$

(b) Max speed when accel = 0

NIL $Mg \sin 30 - T = 0$

$$T = \frac{Mg}{2}$$

\therefore Max speed when Tension in string = $\frac{Mg}{2}$

Now using Hooke's Law $T = \frac{\lambda x}{a}$

$$\frac{Mg}{2} = \frac{6Mg x}{a}$$

$$x = \frac{a}{12}$$

\therefore Max speed occurs after sliding $\frac{a}{12}$ from B.

5) (b) contd

loss in PE = gain in KE + gain in EPE

but $x = \frac{a}{12}$

$$x \sin 30 Mg = \frac{1}{2} Mv^2 + \frac{1}{2} x^2$$

$$\frac{a}{12} \times \frac{1}{2} \times Mg = \frac{1}{2} Mv^2 + \frac{6Mg \left(\frac{a}{12}\right)^2}{2a}$$

$$\frac{ag}{24} = \frac{1}{2} v^2 + \frac{3g}{a} \times \frac{a^2}{144}$$

$$\frac{ag}{24} = \frac{1}{2} v^2 + \frac{ag}{48}$$

$$\frac{1}{2} v^2 = \frac{ag}{48}$$

$$v^2 = \frac{ag}{24}$$

$$v = \sqrt{\frac{ag}{24}}$$

$$(6) (a) \quad M\bar{x} = \rho\pi \int y^2 x \, dx$$

$$\text{where } M = \rho\pi \int y^2 \, dx$$

$$M = \rho\pi \int_0^2 (4-x^2)^2 \, dx$$

$$M = \rho\pi \int_0^2 16 - 8x^2 + x^4 \, dx$$

$$M = \rho\pi \left[16x - \frac{8x^3}{3} + \frac{x^5}{5} \right]_0^2$$

$$M = \rho\pi \left[32 - \frac{64}{3} + \frac{32}{5} \right] = \cancel{\rho\pi} \frac{256\rho\pi}{15}$$

$$\text{Now } \frac{256}{15} \cancel{\rho\pi} \bar{x} = \rho\pi \int_0^2 (4-x^2)^2 x \, dx$$

$$\frac{256}{15} \cancel{\rho\pi} \bar{x} = \int_0^2 16x - 8x^3 + x^5 \, dx$$

$$\frac{256}{15} \cancel{\rho\pi} \bar{x} = \left[8x^2 - 2x^4 + \frac{x^6}{6} \right]_0^2$$

$$\frac{256}{15} \cancel{\rho\pi} \bar{x} = 32 - 32 + \frac{32}{3}$$

$$\bar{x} = \frac{32}{3} \times \frac{15}{256} = \frac{5}{8} \quad \text{As required.}$$

$$(b) \quad \left(\pi \times 4^2 \times l + \frac{256\pi}{15} \right) \rho \bar{x} = \left(\pi \times 4^2 \times l \right) \rho \left(\frac{l}{2} \right) + \frac{256\pi}{15} \rho \left(l + \frac{5}{8} \right)$$

$$\text{Now } \bar{x} = l$$

$$\left(16\pi l + \frac{256\pi}{15} \right) l = 8\pi l^2 + \frac{256\pi l}{15} + \frac{32\pi}{3}$$

$$\cancel{16\pi l^2} + \cancel{\frac{256\pi l}{15}} = \cancel{8\pi l^2}$$

$$\cancel{16\pi l^2} + \cancel{\frac{256\pi l}{15}} = \cancel{8\pi l^2} + \cancel{\frac{256\pi l}{15}} + \frac{32\pi}{3}$$

$$\cancel{16\pi l^2} - \cancel{8\pi l^2} - \cancel{\frac{256\pi l}{15}} + \cancel{\frac{256\pi l}{15}} = 0 \quad l = 1.1 \text{ m}$$

$$(6b) \quad 16\pi l^2 + \frac{256\pi}{\sqrt{3}}l = 8\pi l^2 + \frac{256\pi}{\sqrt{3}}l + \frac{32\pi}{3}$$

$$8\pi l^2 = \frac{32\pi}{3}$$

$$l^2 = \frac{32}{24}$$

$$l^2 = \frac{4}{3}$$

$$l = \frac{2}{\sqrt{3}} \times \frac{\sqrt{3}}{\sqrt{3}} = \frac{2\sqrt{3}}{3}$$