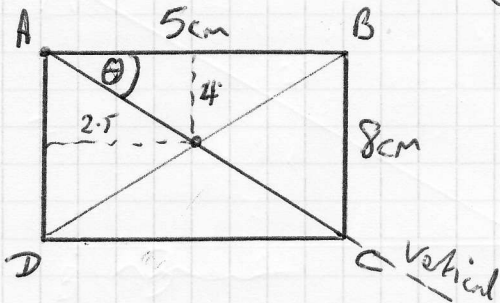


Ex 2C

①

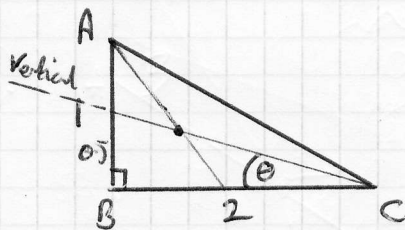


COM @ (2.5, 4)

$$\tan \theta = \frac{4}{2.5}$$

$\theta = 58^\circ$

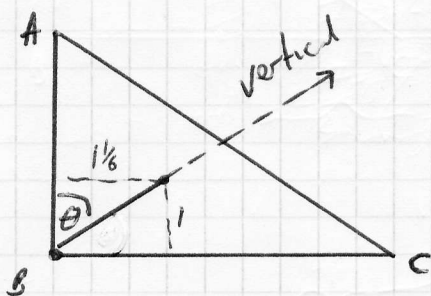
②



$$\tan \theta = \frac{0.5}{2}$$

$\theta = 14^\circ$

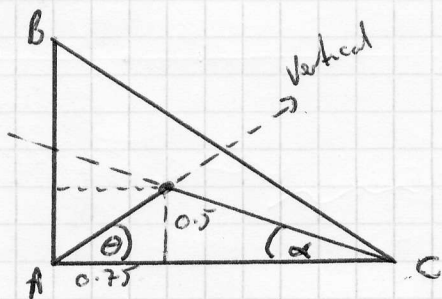
③



$$\tan \theta = \frac{1}{1.5}$$

$\theta = 49.4^\circ$

④



(a)  $\tan \theta = \frac{0.5}{0.75}$

$\theta = 33.7^\circ$

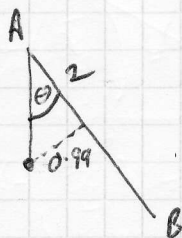
(b)  $\tan \alpha = \frac{0.5}{1.25}$

$\alpha = 21.8^\circ$

$$\left( \frac{\pi \times 2^2}{2} - \frac{\pi \times 1^2}{2} \right) \begin{pmatrix} \bar{x} \\ \bar{y} \end{pmatrix} = 2\pi \begin{pmatrix} 0 \\ 8/3\pi \end{pmatrix} - \frac{\pi}{2} \begin{pmatrix} 0 \\ 4/3\pi \end{pmatrix}$$

$$\frac{3\pi}{2} \begin{pmatrix} \bar{x} \\ \bar{y} \end{pmatrix} = \begin{pmatrix} 0 \\ 14/3 \end{pmatrix}$$

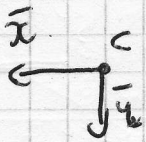
$$\begin{pmatrix} \bar{x} \\ \bar{y} \end{pmatrix} = \begin{pmatrix} 0 \\ 28/9\pi \end{pmatrix} = \begin{pmatrix} 0 \\ 0.99 \end{pmatrix}$$



$$\tan \theta = \frac{0.99}{2}$$

$\theta = 26.3^\circ$

6

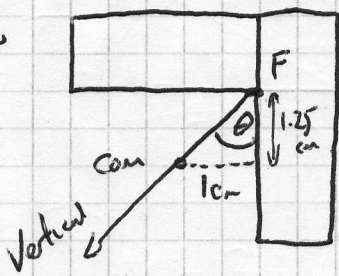


$$(m+3m)\begin{pmatrix} \bar{x} \\ \bar{y} \end{pmatrix} = m\begin{pmatrix} 14 \\ 2.5 \end{pmatrix} + 3m\begin{pmatrix} 2 \\ 7.5 \end{pmatrix}$$

$$4m\begin{pmatrix} \bar{x} \\ \bar{y} \end{pmatrix} = m\begin{pmatrix} 20 \\ 25 \end{pmatrix}$$

$$\begin{pmatrix} \bar{x} \\ \bar{y} \end{pmatrix} = \begin{pmatrix} 5 \\ 6.25 \end{pmatrix}$$

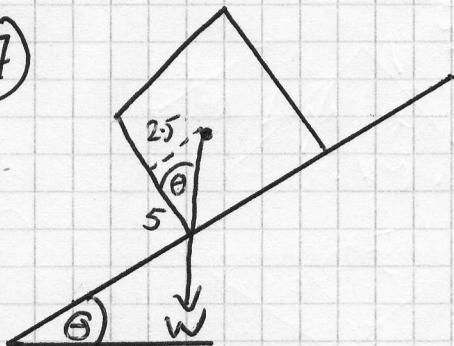
Now



$$\tan \theta = \frac{1}{1.25} \quad \theta = 38.7^\circ$$

Frictionless Peg modelled as a point.

7

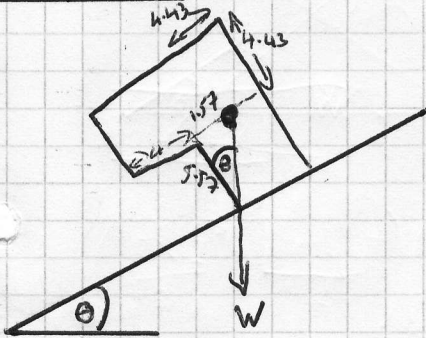


At point of toppling

$$\tan \theta = \frac{2.5}{5}$$

$\theta = 26.6^\circ$   $\therefore$  when slope is at  $25^\circ$ , rectangle remains in equilibrium

8

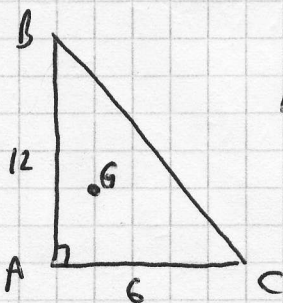


On point of toppling

$$\tan \theta = \frac{1.57}{5.57}$$

$\theta = 15.7^\circ$   $\therefore$  (a) when  $\theta = 10^\circ$  equilibrium ok  
(b) when  $\theta = 25^\circ$  no equilibrium

9



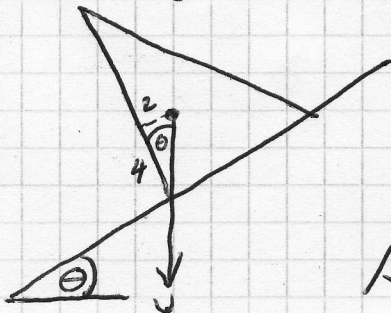
$$\text{Now } G\left(\frac{1}{3} \times 6, \frac{1}{3} \times 12\right) = (2, 4)$$

on point of toppling

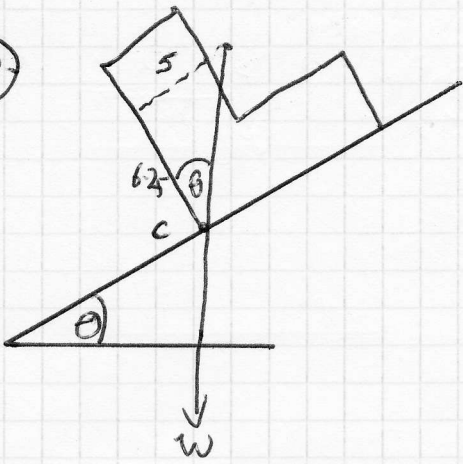
$$\tan \theta = \frac{2}{4} \quad \theta = 26.6^\circ$$

Sliding could have taken place.

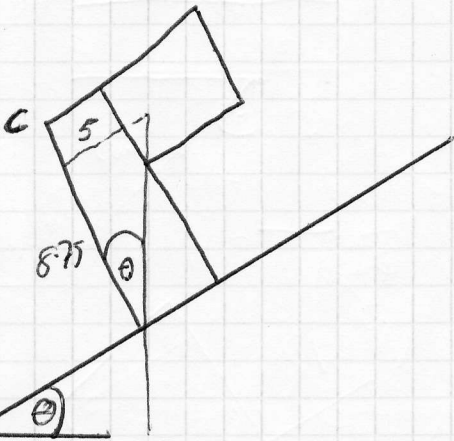
Assume that  $\mu$  is high enough to prevent sliding below this value of  $\theta$ .



(10)



$$\theta_{\text{max}} = \tan^{-1}\left(\frac{5}{6.25}\right) = \underline{38.7^\circ}$$

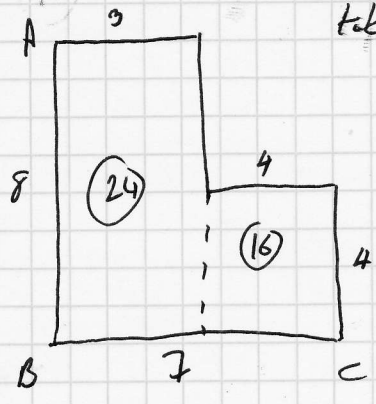


$$\theta_{\text{max}} = \tan^{-1}\left(\frac{5}{8.75}\right) = 29.7^\circ$$

∴ (a) when  $\theta = 10^\circ$  ok.

(b) when  $\theta = 30^\circ$  not ok.

(11)



take A as origin:

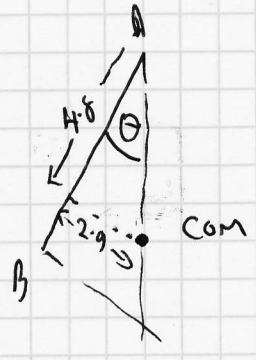
$$(24m + 16m) \begin{pmatrix} \bar{x} \\ \bar{y} \end{pmatrix} = 24m \begin{pmatrix} 1.5 \\ -4 \end{pmatrix} + 16m \begin{pmatrix} 5 \\ -6 \end{pmatrix}$$

$$40 \begin{pmatrix} \bar{x} \\ \bar{y} \end{pmatrix} = \begin{pmatrix} 116 \\ -192 \end{pmatrix}$$

$$\begin{pmatrix} \bar{x} \\ \bar{y} \end{pmatrix} = \begin{pmatrix} 2.9 \\ 4.8 \end{pmatrix}$$

So (a) 2.9 cm from AB and (b) 3.2 from BC

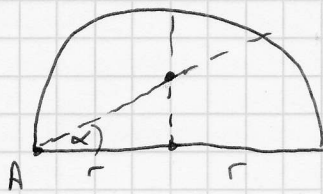
(c)



$$\tan \theta = \frac{2.9}{4.8}$$

$$\theta = 31.1^\circ$$

12



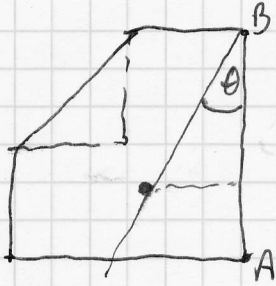
$$\text{COM} = \frac{2r \sin \frac{\pi}{2}}{\frac{3\pi}{2}} = \frac{4r}{3\pi}$$

If suspended from A:  $\tan \alpha = \frac{4r/3\pi}{r}$

$$\tan \alpha = \frac{4}{3\pi}$$

$$\alpha = 0.401^\circ$$

13



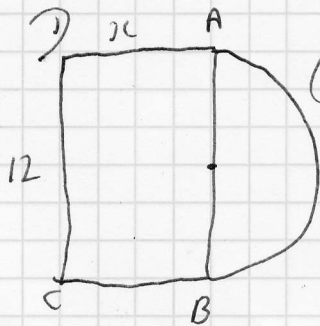
Com from A  $(3\frac{1}{2}, 3\frac{1}{2})$

Com from B  $(3\frac{1}{2}, 8 - 3\frac{1}{2} = 6\frac{1}{2})$

$$\tan \theta = \frac{3\frac{1}{2}}{6\frac{1}{2}}$$

$$\theta = 42.6^\circ$$

14



$$(a) (12x\mu + \frac{\pi \cdot 6^2}{2}\mu) \bar{x} = 12x\mu \left(\frac{x}{2}\right) + 18\pi\mu \left(x + 2.6 \cdot \frac{6}{\pi}\right)$$

$$(12x + 18\pi) \bar{x} = 6x^2 + 18\pi \left(x + \frac{8}{\pi}\right)$$

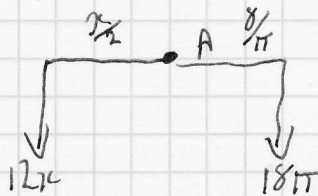
$$12x^2 + 18\pi x = 6x^2 + 18\pi x + 144$$

$$6x^2 - 144 = 0$$

$$x^2 = 24$$

$$x = \sqrt{24} = 2\sqrt{6} = 4.9$$

Alternatively: centre of mass lies on AB so balanced

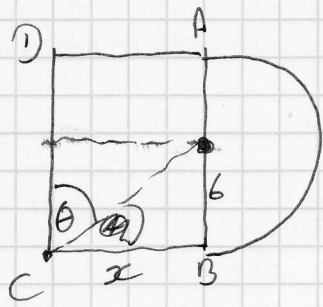


Equilib about A:  $12x \cdot \frac{x}{2} = \frac{8}{\pi} \cdot 18\pi$

$$6x^2 = 144$$

$$x = 4.9$$

(14) (b)



$$\tan \theta = \frac{15}{\sqrt{24}}$$

$$\tan \theta = \frac{x}{b} = \frac{\sqrt{24}}{6} = 39.2^\circ$$